ames Minardi

641-373-6387 • JamesMinardiP@gmail.com • in/JamesMinardi • JamesMinardi.com

EXPERIENCE

GARMIN

Embedded Graphics Engineer | Internship

- Develop and maintain multithreaded Vulkan and OpenGL graphics libraries for next-gen flight decks & displays
- Implement DirectX library significantly reducing code reuse across multiple products
- Redesign flight deck simulator architecture to establish proper library ownership of graphics code
- Automated software requirement tracing in Python, meeting FAA regulations and reducing engineer person-hours

Musco Sports Lighting

Software Engineer | Internship

- Designed and implemented a next-gen AI and video processing platform to reduce development time & code reuse
- Developed Linux bash scripts to perform debugging services on hundreds of NVIDIA Jetson devices automatically
- Created active CI/CD pipelines for testing, staging, and production environments with Git integration

BAE Systems, Inc.

Embedded Software Engineer | Co-op

- Implemented linear algebra and combinatorial algorithms to satisfy hardware and systems requirements for high-performance, real-time, embedded GPS receivers
- Contributed 10,000+ lines of production code, optimizing for performance, memory, and power requirements
- Increased existing code coverage by 30% in unit and integration tests using Google Test
- Advocated for and designed better C/C++ coding practices to promote efficient code development

Iowa State University

Resident Assistant | Part-time

- Represented and served all RAs on campus under department leadership as Vice President
- · Fostered the development of an inclusive community of over 70 residents

PROJECTS

OpenGL-Compliant GPU | *FPGA, C++, VHDL, Xilinx Vivado, AXI, DMA*

- Designed and developed an OpenGL-compliant GPU architecture on an Xilinx FPGA using VHDL
- Implemented rasterization algorithms to reduce traversal/interpolation time and resource consumption
- Designed vertex and fragment shader IP cores to execute GLSL instructions on the GPU
- Managed data flow from custom OpenGL drivers to the GPU using direct memory access (DMA)

Procedural Terrain Generation | *WebGPU, C++, Emscripten, GLM, GLFW, ImGui*

- Implemented procedural terrain using configurable noise types such as fBm, Perlin, and Value noise
- Developed for cross-platform compatibility using C++ and Emscripten

Machine Learning Hardware Accelerator | FPGA, Xilinx Vivado, VHDL, AXI, DMA, C++, Python

- Developed a hardware accelerator for a self-trained image classification model on an FPGA
- Implemented deep learning optimizations including quantization, data reuse, tiling, and SIMD

Pipelined CPU | VHDL, MIPS Assembly, Hardware Architecture

- Designed a MIPS assembly pipelined CPU architecture while considering critical paths and hazards
- Optimized performance using hazard detection and forwarding, resulting in a 60% speedup
- Analyzed test bench waveforms by hand and automatically to debug the hardware design

Autonomous Roomba Robot | Embedded C

- Developed bare metal drivers for an ARM Cortex M-4 processor robot to navigate an obstacle course
- Features UART communication, IR sensors using ADC, Sonar sensors using PWM timers, and more

SKILLS

Languages: C, C++, Python, Bash, Make, CMake, GLSL / WGSL / HLSL
Frameworks: OpenGL, Vulkan, WebGPU, WebGL, AMBA (AXI, AHB, APB), Win32, Google Test
Tools: RenderDoc, Xilinx Vivado, Intel Quartus, Vitis, Git, SVN, MATLAB
Topics: Computer Graphics, Raytracing, FPGA RTL Design, HW Architecture, Data Structures & Algorithms

EDUCATION

Iowa State University, Bachelor of Science Computer Engineering May – August 2024

May – August 2023

June 2022 – April 2023

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July 2021 - May 2024